

#### **Texas Instruments Wiki**

### Blink your first LED

#### From Texas Instruments Wiki

Blink your first LED

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### My First MSP430 LaunchPad Project

In this project, we will learn a few things:

- How to create a new project with Code Composer Studio
- Learn how to blink the on-board Red LED on the MSP430 LaunchPad
- Change the speed of the blinking Red LED
- Learn how to toggle between the Red and Green LED

## Things you'll need

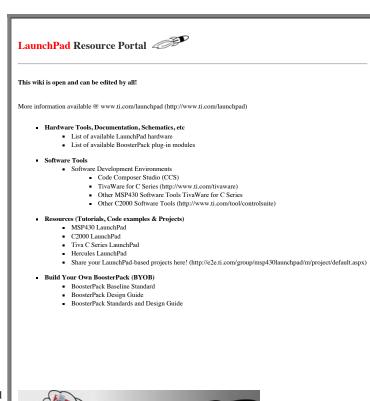
- MSP430 LaunchPad Evaluation Kit (MSP-EXP430G2) -- Get one here! (https://estore.ti.com/MSP-EXP430G2-MSP430-LaunchPad-Value-Line-Development-kit-P2031.aspx)
- 2. Code Composer Studio (Software Development Environment) -- Download & install it
- 3. 10 minutes

# **Hardware Setup**

- The MSP430 LaunchPad kit includes everything you need out of the box. To start
  programming your MSP430 LaunchPad, you'll first have to install Code Composer
  Studio onto your computer. This will install all of the required drivers for your new
  MSP430 LaunchPad kit.
- Next, simply plug in your LaunchPad with the included USB cable to your Windows PC. The green power (PWR) LED should glow.
- 3. If prompted, let Windows automatically install the software.

## Creating a new Code Composer Studio Project

- 1. Now that our hardware is setup, we will open up Code Composer Studio. As it is opening, CCS will ask you to select a workspace.
- Since this is our first project, we'll create a new one called "LaunchPad\_Projects". A workspace is where all of your Code Composer Studio projects will live. Once created, press OK

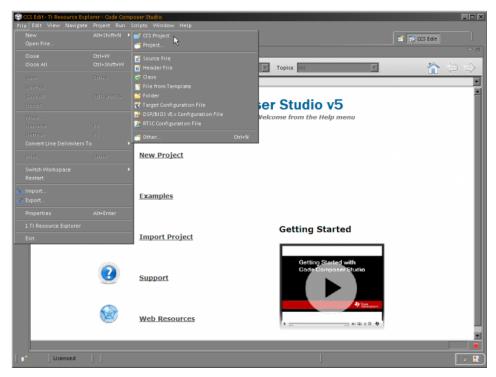




MSP-EXP430G2 LaunchPad Project Zero



3. Once CCS is opened, we can create a new project by going to toFile > New > CCS Project



4. This will open up the "New CCS Project" Window. Within this window, we need to do 2 things. Name our project & choose our *Device Variant*. Let's name our project "Blink\_LED"

We also need to choose the appropriate MSP430 device. For this tutorial, we will program the MSP430G2553 device that comes pre-populated on the MSP430 LaunchPad. (Due to the simplicity of this particular tutorial, any of the MSP430G2xx devices will work for this example!)
Then, click "Finish"



# **Writing Code**

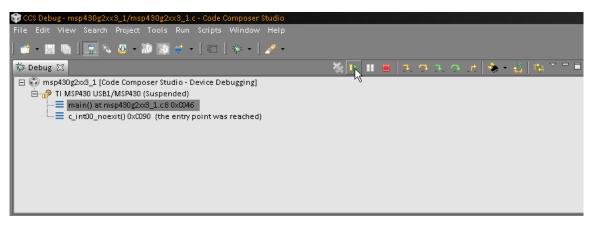
1. Now, we have our blank canvas! We can finally start writing code!

```
#include <msp430g2553.h>
 unsigned int i = 0;
                                                     // Initialize variables. This will keep count of how many cycles between LED toggles
void main(void)
  WDTCTL = WDTPW + WDTHOLD;
                                                    // Stop watchdog timer. This line of code is needed at the beginning of most MSP430 projects.
                                                    // This line of code turns off the watchdog timer, which can reset the device after a certain period of time.
 P1DIR |= 0x01;
                                                    // PlDIR is a register that configures the direction (DIR) of a port pin as an output or an input.
                                                    // To set a specific pin as output or input, we write a '1' or '0' on the appropriate bit of the register.
                                                    // P1DTR = <PTN7><PTN6><PTN5><PTN4><PTN3><PTN2><PTN1><PTN0>
                                                    // Since we want to blink the on-board red LED, we want to set the direction of Port 1, Pin 0 (Pl.0) as an output
                                                    // We do that by writing a 1 on the PINO bit of the P1DIR register
// P1DIR = <PIN7><PIN6><PIN5><PIN4><PIN3><PIN2><PIN1><PIN1></PIN0>
// P1DIR = 0000 0001
                                                    // P1DIR = 0x01
                                                                           <-- this is the hexadecimal conversion of 0000 0001
                                                    // This empty for-loop will cause the lines of code within to loop infinitely
  for (;;)
    P10UT ^= 0x01;
                                                    // Toggle P1.0 using exclusive-OR operation (^=)
                                                    // PlOUT is another register which holds the status of the LED. // '1' specifies that it's ON or HIGH, while '0' specifies that it's OFF or LOW // Since our LED is tied to Pl.0, we will toggle the 0 bit of the PlOUT register
    for(i=0; i< 20000; i++);
                                                    // Delay between LED toggles. This for-loop will run until the condition is met.
                                                    //In this case, it will loop until the variable i increments to 20000.
  }
```

1. Now that we have written our code, we can download it to our MSP430 LaunchPad that is plugged into the USB port! We can do this by clicking the debug button



2. Clicking the Debug button will take us to the CCS Debug View. Here, we can press the Run button to start running the code we just wrote.



3. At this point, your Red LED should be blinking! Congratulations!

#### Other exercises!

- 1. Now that we have our LED blinking, play around with the number inside of the for-loop to change the speed of the blinking LED. The smaller the number, the shorter the delay between LED toggles. Alternatively, the larger the number, the longer the delay. Try values like 5000, 40000, etc.
- 2. Another exercise is getting the green LED to blink as well. The green LED is tied to Port P1.6. Using the P1DIR and P1OUT registers we used above, see if you can get both LEDs to blink. Can you make them blink in unison? Can you make them blink alternatively?

Be sure to check out more resources for the MSP-EXP430G2 LaunchPad here!



For technical support please post your questions at http://e2e.ti.com. Please post only comments about the article **Blink your first LED** here.

#### Links



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